

# High Accuracy Ambient Light Sensor With I<sup>2</sup>C Interface



## LINKS TO ADDITIONAL RESOURCES



### DESCRIPTION

VEML6031X00 is a high accuracy ambient light digital 16-bit resolution sensor in a miniature opaque 2.67 mm x 2.45 mm package. It includes a high sensitive photodiode, a low noise amplifier, a 16-bit A/D converter and supports an easy to use I<sup>2</sup>C bus communication interface and additional interrupt feature.

The ambient light result is as digital value available.

### **APPLICATIONS**

Ambient light sensor in automotive for

- Display backlight controls
- Infotainment systems
- Rear view mirror dimming
- · Interior lighting control systems
- Head-up displays

### **FEATURES**

- Package type: surface-mount
- Dimensions (L x W x H in mm): 2.67 x 2.45 x 0.6
- AEC-Q100 gualified
- Integrated modules: ambient light sensor (ALS)
- Supply voltage range V<sub>DD</sub>: 2.5 V to 3.6 V
- Communication via I<sup>2</sup>C interface
- I<sup>2</sup>C bus H-level range: 1.7 V to 3.6 V
- · Floor life: 4 weeks, MSL 2a, according to J-STD-020
- Low shut down current consumption: typ. 0.5 µA
- Material categorization: for definitions of compliance please see www.vishav.com/doc?99912

### AMBIENT LIGHT FUNCTION

- Filtron<sup>TM</sup> technology adaption: close to real human eye response
- Typical ALS output tolerance of  $\leq$  10 % under different light sources
- 16-bit dynamic range for ambient light detection from 0 lx to about 228 klx with resolution down to 0.0034 lx/ct, supports low transmittance (dark) lens design
- Excellent temperature compensation
- High dynamic detection resolution

PRODUCT SUN	IMARY					
PART NUMBER	OPERATING VOLTAGE RANGE (V)	I <sup>2</sup> C BUS VOLTAGE RANGE (V)	AMBIENT LIGHT RANGE (lx)	AMBIENT LIGHT RESOLUTION (lx)	OUTPUT CODE	ADC RESOLUTION PROXIMITY / AMBIENT LIGHT
VEML6031X00	2.5 to 3.6	1.7 to 3.6	0 to 228 000	0.0034	16 bit, I <sup>2</sup> C	- / 16 bit

ORDERING INFORMATION								
ORDERING CODE	PACKAGING	VOLUME <sup>(1)</sup>	REMARKS					
VEML6031X00	Tape and reel	MOQ: 3000	2.67 mm x 2.45 mm x 0.6 mm					
VEML6031X00-GS15	Tape and reel	MOQ: 10 000	2.67 mm x 2.45 mm x 0.6 mm					
VEML60311X00	Tape and reel	MOQ: 3000	2.67 mm x 2.45 mm x 0.6 mm					
VEML60311X00-GS15	Tape and reel	MOQ: 10 000	2.67 mm x 2.45 mm x 0.6 mm					

#### Note

<sup>(1)</sup> MOQ: minimum order quantity

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e RoHS COMPLIANT HALOGEN FREE GREEN

(5-2008)





SLAVE ADDRESS OPTIONS				
ORDERING CODE	SLAVE ADDRESS (7 bit)			
VEML6031X00	0x29			
VEML60311X00	0x10			

<b>ABSOLUTE MAXIMUM RATINGS</b> (T <sub>amb</sub> = 25 °C, unless otherwise specified)									
PARAMETER	TEST CONDITION	SYMBOL	MIN.	MAX.	UNIT				
Supply voltage		V <sub>DD</sub>	0	3.6	V				
Operation temperature range		T <sub>amb</sub>	-40	+110	°C				
Storage temperature range		T <sub>stg</sub>	-40	+110	°C				
Total power dissipation	T <sub>amb</sub> ≤ 25 °C	P <sub>tot</sub>	-	50	mW				
Junction temperature		Τ <sub>i</sub>	_	110	°C				

<b>BASIC CHARACTERISTICS</b> (T <sub>amb</sub> = 25 °C, unless otherwise specified)										
PARAMETER	TEST CONDITION	SYMBOL	MIN.	TYP.	MAX.	UNIT				
Supply voltage		V <sub>DD</sub>	2.5	3.3	3.6	V				
	$V_{DD} = V_{BUS}$		-	0.5	-					
Shut down current <sup>(1)</sup>	$V_{DD} = V_{BUS} = 3.0 V$	I <sub>sd</sub>	-	-	1.2	μA				
Shut down current <sup>(1)</sup> Active mode current I <sup>2</sup> C clock rate range I <sup>2</sup> C bus input H-level range I <sup>2</sup> C bus input L-level range Digital current out (low, current sink)	$V_{DD}$ is 3.6 V and $V_{BUS}$ = 1.7 V		-	3.1	-					
Active mode current	V <sub>DD</sub> is 3.3 V	I <sub>DD</sub>	-	280	-	μA				
I <sup>2</sup> C clock rate range		f <sub>SCL</sub>	10	-	400	kHz				
12C bus input H loval range	$V_{BUS} = V_{DD}$	V <sub>ih</sub>	0.7 x V <sub>DD</sub>	-	3.6	V				
1-C bus input H-level range	V <sub>BUS</sub> ≠ V <sub>DD</sub>	V <sub>ih</sub>	$0.85 \times V_{BUS}$	-	3.6	V				
12C bus input L lovel range	$V_{BUS} = V_{DD}$	V <sub>il</sub>	-0.3	-	$0.3 \times V_{DD}$	V				
I-C bus input E-level range	V <sub>BUS</sub> ≠ V <sub>DD</sub>	V <sub>il</sub>	-0.3	-	$0.2 \text{ x V}_{\text{BUS}}$	V				
Digital current out (low, current sink)		I <sub>ol</sub>	3	-	-	mA				
Digital resolution (LSB count) <sup>(2)</sup>	With ALS_GAIN = x 2, ALS_IT = 400 ms, PD_DIV4 = 4/4 PD		-	0.0034	-	lx/step				
Detectable maximum illuminance	With ALS_GAIN = x 0.5, ALS_IT = $6.25$ ms, PD_DIV4 = $1/4$ PD	E <sub>V max.</sub>	-	228 000	-	lx				
ALS dark offset (1)	With ALS_GAIN = x 2, IT = 200 ms, PD_DIV4 = 4/4 PD		-	4	-	step				
IR dark offset <sup>(1)</sup>	With ALS_GAIN = x 2, IT = 200 ms, PD_DIV4 = 4/4 PD		-	4	-	step				

Notes

(1) Light conditions: dark

<sup>(2)</sup> Light conditions:  $E_V = 100$  lx with 4300K white LED

### **CIRCUIT BLOCK DIAGRAM**



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I <sup>2</sup> C TIMING CHARACTERISTICS (T <sub>amb</sub> = 25 °C, unless otherwise specified)								
DADAMETED	SYMBOL	STANDAR	D MODE <sup>(1)</sup>	FAST MODE <sup>(1)</sup>				
FARAMETER	STMBOL	MIN.	MAX.	MIN.	MAX.	UNIT		
Clock frequency	f <sub>(SMBCLK)</sub>	10	100	10	400	kHz		
Bus free time between start and stop condition	t <sub>(BUF)</sub>	4.7	-	1.3	-	μs		
Hold time after (repeated) start condition; after this period, the first clock is generated	t <sub>(HDSTA)</sub>	4.0	-	0.6	-	μs		
Repeated start condition setup time	t <sub>(SUSTA)</sub>	4.7	-	0.6	-	μs		
Stop condition setup time	t <sub>(SUSTO)</sub>	4.0	-	0.6	-	μs		
Data hold time	t <sub>(HDDAT)</sub>	0	3450	0	900	ns		
Data setup time	t <sub>(SUDAT)</sub>	250	-	100	-	ns		
I <sup>2</sup> C clock (SCK) low period	t <sub>(LOW)</sub>	4.7	-	1.3	-	μs		
I <sup>2</sup> C clock (SCK) high period	t <sub>(HIGH)</sub>	4.0	-	0.6	-	μs		
Detect clock / data low timeout	t <sub>(TIMEOUT)</sub>	25	35	-	-	ms		
Clock / data fall time	t <sub>(F)</sub>	_	300	_	300	ns		
Clock / data rise time	t <sub>(R)</sub>	-	1000	-	300	ns		

#### Note

<sup>(1)</sup> Data based on standard I<sup>2</sup>C protocol requirement, not tested in production





Fig. 2 - I<sup>2</sup>C Timing Diagram



PARAMETER TIMING INFORMATION

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Fig. 3 - I<sup>2</sup>C Bus Timing for Sending Word Command Format



Fig. 4 - I<sup>2</sup>C Bus Timing for Receive Word Command Format



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### BASIC CHARACTERISTICS (T<sub>amb</sub> = 25 °C, unless otherwise specified)



Fig. 5 - Relative Sensitivity, ALS Channel vs. Wavelength



Fig. 6 - Relative Sensitivity, IR Channel vs. Wavelength



Fig. 7 - Relative Sensitivity vs. Angular Displacement



Fig. 8 - Relative Deviation, ALS Channel vs. Temperature (at lux levels lower than ~200 lux, dark current effects should be taken into account, ref. Fig. 9)



Fig. 9 - Dark Current Offset vs. Ambient Temperature





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### **APPLICATION INFORMATION**

Special care must be taken into consideration when handling the VEML6031X00. VEML6031X00 is sensitive to dust and scratches, proper optical device handling procedures are recommended.

The optical surface of the device must be kept clean for optimal performance in both prototyping with the device and mass production manufacturing procedures. Tweezers with plastic or rubber contact surfaces are recommended to avoid scratches on the optical surface. Avoid manipulation with metal tools when possible. The optical surface must be kept clean of fingerprints, dust, and other optical-inhibiting contaminants.

If the device optical surface requires cleaning, the use of isopropyl alcohol is recommended. A few gentle brushes with a soft swab are appropriate. Avoid potentially abrasive cleaning and manipulating tools and excessive force that can scratch the optical surface.

If the VEML6031X00 performs less than optimally, inspect the optical surface for dirt, scratches, or other optical artifacts.

VEML6031X00 is a cost effective solution of ambient light sensor with I<sup>2</sup>C bus interface. The standard serial digital interface is easy to access "Ambient Light Signal" without complex calculation and programming by external controller. Beside the digital output also a flexible programmable interrupt pin is available.

#### **1. Application Circuit**



#### Notes

• The interrupt pin is an open drain output. Proposed values for the pull-up resistors should be > 1 k $\Omega$ , e.g. 2.2 k $\Omega$  to 4.7 k $\Omega$  for the R1 and R2 (at SDA and SCL) and 10 k $\Omega$  to 100 k $\Omega$  for R3 (at interrupt).

Normally just one decoupling capacitor is needed. This should be  $\geq$  100 nF and placed close to the V<sub>DD</sub> pin.

For detailed description about set-up and use of the interrupt as well as more application related information see AN: "Designing VEML6031X00 into an Application".



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#### 2. I<sup>2</sup>C Interface

The VEML6031X00 has eighteen register addresses responsible for operation control, parameter setup and result buffering. All registers are accessible via I<sup>2</sup>C communication. Fig. 9 shows the basic I<sup>2</sup>C communication with VEML6031X00.

The built in I<sup>2</sup>C interface is compatible with I<sup>2</sup>C modes "standard" and "fast": 10 kHz to 400 kHz.

Please refer to the I<sup>2</sup>C specification from NXP for details.





Fig. 12 - Send Byte / Receive Byte Protocol

#### **Device Address**

The VEML6031X00 is available in two different pre-configured slave addresses.

For one version the predefined 7 bit  $I^2C$  bus address is set to 0101001 = 0x29. The least significant bit (LSB) defines read or write mode. Accordingly the bus address is set to 0101 0010 = 0x52 for write and 0101 0011 = 0x53 for read. The second version comes with predefined 7 bit  $I^2C$  bus address of 0010000 = 0x10, so, here the write address is 0010 0000 = 0x20 for write and 0010 0001 = 0x21 for read.

#### **Register Addresses**

The VEML6031X00 has eighteen registers, accessible through there respective 8-bit command codes.

The registers are 0x00 to 0x17 (0x02 and 0x03, 0x08 to 0x0F and 0x16 are not defined / reserved). Note that due to the location of the two shutdown bits (SD and ALS\_IR\_SD), one in register 0x00 and the other in 0x01, it is necessary to always write to both registers at once when configuring the device.

#### Auto-Memorization

The VEML6031X00 stores the last measured ambient data before the device is shutdown, keeping the data accessible. When VEML6031X00 is in shutdown mode, the host can freely read this data via read command directly.



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COMMAND R	COMMAND REGISTER FORMAT								
COMMAND CODE	REGISTER NAME	BIT	DEFAULT VALUE	FUNCTION / DESCRIPTION	R/W				
0x00	ALS_CONF 0	0:7	0x01	ALS integration time, measurement mode, shutdown	R/W				
0x01	ALS_CONF 1	0:7	0x00	ALS and IR shutdown, ALS gain, interrupt persistance	R/W				
0x04	ALS_WH_L	0:7	0x00	ALS high threshold window setting (LSB)	R/W				
0x05	ALS_WH_H	0:7	0x00	ALS high threshold window setting (MSB)	R/W				
0x06	ALS_WL_L	0:7	0x00	ALS low threshold window setting (LSB)	R/W				
0x07	ALS_WL_H	0:7	0x00	ALS low threshold window setting (MSB)	R/W				
0x10	ALS_DATA_L	0:7	0x00	Low byte of 16-bit ALS result DATA	R				
0x11	ALS_DATA_H	0:7	0x00	High byte of 16-bit ALS result DATA	R				
0x12	IR_DATA_L	0:7	0x00	Low byte of 16-bit IR result DATA	R				
0x13	IR_DATA_H	0:7	0x00	High byte of 16-bit IR result DATA	R				
0x14	ID_L	0:7	0x01	ID code	R				
0x15	ID_H	0:7	0x00	Package and version code	R				
0x17	ALS_INT	0:7	0x00	ALS INT trigger event	R				

#### Notes

• Command code 0x00 default value is 0x01 = device is shutdown

• Command 0x00 and command 0x01 must be executed together, they cannot be executed independently

TABLE 1 - RE	GISTER: ALS_C	CONF_0 - 0x00	
REGISTER NAME	BIT	FUNCTION / DESCRIPTION	R/W
Reserved	7	Must be set to "0"	R/W
ALS_IT	6:4	ALS integration time setting 000 = 3.125 ms 001 = 6.25 ms 010 = 12.5 ms 011 = 25 ms 100 = 50 ms 101 = 100 ms 110 = 200 ms 111 = 400 ms	R/W
ALS_AF	3	Active force mode enable setting 0 = AF disable 1 = AF enable Once enabled, a single measurement can be triggered with the "ALS_TRIG" bit	R/W
ALS_TRIG	2	ALS active force trigger setting 0 = no active force mode trigger 1 = trigger active force mode This bit resets to "0" automatically after every trigger	R/W
ALS_INT_EN	1	ALS interrupt setting 0 = interrupt disable 1 = interrupt enable	R/W
SD	0	Band gap and LDO shutdown setting 0 = band gap and LDO on 1 = band gap and LDO shutdown (default)	R/W

#### Note

• Command code 0x00 default value is 0x01 = device is shutdown



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TABLE 2 - REGISTER: ALS_CONF_1 - 0x01						
REGISTER NAME	BIT	FUNCTION / DESCRIPTION	R/W			
ALS_IR_SD	7	ALS and IR channel shutdown setting 0 = ALS and IR channels on 1 = ALS and IR channels shutdown	R/W			
PD_DIV4	6	Effective photodiode size ALS and IR 0 = 4/4 PD used 1 = 1/4 PD used	R/W			
Reserved	5	Reserved	R/W			
ALS_GAIN	4:3	Gain selection 00 = ALS gain x1 01 = ALS gain x2 10 = ALS gain x 0.66 11 = ALS gain x 0.5	R/W			
ALS_PERS	2:1	ALS persistence protect number setting Number of persistent measurements above threshold to trigger the interrupt 00 = 1 01 = 2 10 = 4 11 = 8	R/W			
ALS_CAL	0	Must be set to "1" when power on ready	R/W			

TABLE 3 - REGISTER: ALS_WH - 0x04, 0x05						
COMMAND CODE	REGISTER NAME	BIT	FUNCTION / DESCRIPTION	R/W		
0x04	ALS_WH_L	7:0	ALS high threshold window setting (data byte low)	R/W		
0x05	ALS_WH_H	7:0	ALS high threshold window setting (data byte high)	R/W		

TABLE 4 - REGISTER: ALS_WL - 0x06, 0x07						
COMMAND CODE	REGISTER NAME	BIT	FUNCTION / DESCRIPTION	R/W		
0x06	ALS_WL_L	7:0	ALS low threshold window setting (data byte low)	R/W		
0x07	ALS_WL_H	7:0	ALS low threshold window setting (data byte high)	R/W		

TABLE 5 - REGISTER: ALS_DATA - 0x10, 0x11							
COMMAND CODE	REGISTER NAME	BIT	FUNCTION / DESCRIPTION	R/W			
0x10	ALS_DATA_L	7:0	ALS result channel (data byte low)	R			
0x11	ALS_DATA_H	7:0	ALS result channel (data byte high)	R			

TABLE 6 - REGISTER: IR_DATA - 0x12, 0x13						
COMMAND CODE	REGISTER NAME	BIT	FUNCTION / DESCRIPTION	R/W		
0x12	IR_DATA_L	7:0	IR result channel (data byte low)	R		
0x13	IR_DATA_H	7:0	IR result channel (data byte high)	R		

TABLE 7 - REGISTER: ID - 0x14, 0x15						
COMMAND CODE	REGISTER NAME	BIT	FUNCTION / DESCRIPTION	R/W		
0x14	ID_L	7:0	ID code: 0x01	R		
0x15	ID_H	7:6 5:4 3:0	Package code: 00 Slave address: 00 = 0x29; 01 = 0x10 Version code: 0000 = A01	R		

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TABLE 8 - REGISTER: ALS_INT - 0x17							
REGISTER NAME	BIT	FUNCTION / DESCRIPTION	R/W				
Reserved	7:4	Reserved	R				
ALS_AF_DATA_READY	3	ALS active force mode data ready flag	R				
ALS_IF_L	2	ALS low threshold INT flag	R				
ALS_IF_H	1	ALS high threshold INT flag	R				
Reserved	0	Reserved	R				

### CALCULATING THE LUX LEVEL

Command code 0x10 and 0x11 contain the results of the ALS measurement. This 16-bit code needs to be converted to a decimal value to determine the corresponding lux value. The calculation of the corresponding lux level is dependent on the programmed gain setting and the chosen integration time.

The component is most sensitive with ALS\_GAIN = x2, PD\_DIV4 = 4/4 and an integration time of 400 ms, specified to 0.0034 lx/step.

Every time the integration time is halved, the resolution is doubled but also the possible detection range is doubled.

The same principle is valid for the gain setting. For ALS\_GAIN = x1 it is doubled. For PD\_DIV4 = 1/4 the size of the photodiode is just 1/4, so, also the sensitivity is just 1/4, resolution and max. possible detection range is times 4, to allow for higher illuminations up to about 228 klx.

TABLE 9 - RESOLUTION AND MAXIMUM DETECTION RANGE AT PD_DIV4 = 0 (= $x 4/4$ )									
	GAIN x 2	GAIN x 1	GAIN x 0.66	GAIN x 0.5		GAIN x 2	GAIN x 1	GAIN x 0.66	GAIN x 0.5
IT (ms) TYPICAL RESOLUTION (lx/cnt)						MAXIMUM POSSIBLE ILLUMINATION (Ix)			
400	0.0034	0.0068	0.0103	0.0136		223	446	675	891
200	0.0068	0.0136	0.0206	0.0272		446	891	1350	1783
100	0.0136	0.0272	0.0412	0.0544		891	1783	2701	3565
50	0.0272	0.0544	0.0824	0.1088		1783	3565	5402	7130
25	0.0544	0.1088	0.1648	0.2176		3565	7130	10803	14260
12.5	0.1088	0.2176	0.3297	0.4352		7130	14260	21607	28521
6.25	0.2176	0.4352	0.6594	0.8704		14260	28521	43213	57042
3.125	0.4352	0.8704	1.3188	1.7408		(-) <sup>(1)</sup>	(-) <sup>(1)</sup>	(-) (1)	(-) (1)

TABLE 10 - RESOLUTION AND MAXIMUM DETECTION RANGE AT PD_DIV4 = 1 (= x 1/4)									
	GAIN x 2	GAIN x 1	GAIN x 0.66	GAIN x 0.5		GAIN x 2	GAIN x 1	GAIN x 0.66	GAIN x 0.5
IT (ms)	-	TYPICAL RESC	LUTION (lx/cnt	)		MAXIMUM POSSIBLE ILLUMINATION (Ix)			
400	0.0136	0.0272	0.0412	0.0544		891	1783	2701	3565
200	0.0272	0.0544	0.0824	0.1088		1783	3565	5402	7130
100	0.0544	0.1088	0.1648	0.2176		3565	7130	10803	14260
50	0.1088	0.2176	0.3297	0.4352		7130	14260	21607	28521
25	0.2176	0.4352	0.6594	0.8704		14260	28521	43213	57042
12.5	0.4352	0.8704	1.3188	1.7408		28521	57042	86427	114083
6.25	0.8704	1.7408	2.6376	3.4816		57042	114083	172854	228167
3.125	1.7408	3.4816	5.2752	6.9632		(-) (1)	(-) (1)	(-) (1)	(-) (1)

#### Note

(1) For integration time of 3.125 ms the maximum count level is no longer 16 bit, so, half the integration time no longer leads to double the max. lux level

Example:

If the 16-bit word of the ALS data shows: 0000 0101 1100 1000 = 1480 (dec.), the programmed ALS\_GAIN = x1, PD\_DIV4 = 4/4 (= x1) and ALS\_IT = 100 ms, the corresponding lux level is: light level (1x) = 1480 x 0.0272 = 40.256 lx.

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### **PACKAGE DIMENSIONS** in millimeters









Pin 1 marking: exposed pad offset





Drawing No.: 6.550-5357.01-4 Issue: 1; 14.04.2021

All dimensions in mm incl. burrs Not indicated tolerances ± 0.1





#### **MARKING AND PIN 1 IDENTIFICATION**



Y: year WW: week XXX: lot number

#### TAPE AND REEL DIMENSIONS in millimeters



Drawing No.: 9.800-5148.01-4 Issue: prelminary; 16.10.19

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12 ns. contact: sensorster



### DRYPACK

Devices are packed in moisture barrier bags (MBB) to prevent the products from moisture absorption during transportation and storage. Each bag contains a desiccant.

### **FLOOR LIFE**

Floor life (time between soldering and removing from MBB) must not exceed the time indicated on MBB label:

Floor life: 4 weeks

Conditions:  $T_{amb}$  < 30 °C, RH < 60 %

Moisture sensitivity level 2a, according to J-STD-020.

### DRYING

In case of moisture absorption devices should be baked before soldering. Conditions see J-STD-020 or label. Devices taped on reel dry using recommended conditions 192 h at 40 °C (+ 5 °C), RH < 5 %.

## **REFLOW SOLDER PROFILE**







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